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Spectral characterization of matchings in graphs

**LINEAR
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Applications

Keivan Hassani Monfared ^a*,*∗*,*¹, Sudipta Mallik ^b

^a *University of Calgary, Canada* ^b *Department of Mathematics & Statistics, Northern Arizona University, 805 S. Osborne Dr., PO Box: 5717, Flagstaff, AZ 86011, USA*

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A spectral characterization of the matching number (the size of a maximum matching) of a graph is given. More precisely, it is shown that the graphs *G* of order *n* whose matching number is *k* are precisely those graphs with the maximum skew rank 2*k* such that for any given set of *k* distinct nonzero purely imaginary numbers there is a real skew-symmetric matrix *A* with graph *G* whose spectrum consists of the given *k* numbers, their conjugate pairs and $n - 2k$ zeros.

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1. Introduction

A *matching* in a graph *G* is a set of vertex-disjoint edges. A *maximum matching* in *G* is a matching with the maximum number of edges among all matchings in *G*.

^{*} Corresponding author.

E-mail addresses: k1monfared@gmail.com (K. Hassani Monfared), sudipta.mallik@nau.edu (S. Mallik).

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A *perfect matching* in a graph *G* on *n* vertices is a maximum matching consisting of $\frac{n}{2}$ edges. Matchings are well-studied combinatorial objects with practical applications such as Hall's marriage theorem (1935). For a full treatment of matchings see [\[6\].](#page-12-0) In 1947 Tutte gave necessary and sufficient conditions for a graph to have a perfect matching.

Theorem 1.1. *(See [\[7\].](#page-12-0)) A graph G has a perfect matching if and only if for each vertex subset* S *of* G *, the number of odd components of* $G - S$ *is at most* $|S|$ *.*

The matching number, denoted by match (G) , of a graph G is the number of edges in a maximum matching in *G*. So Theorem 1.1 characterizes all graphs *G* on *n* vertices with match $(G) = \frac{n}{2}$. In this article we give another set of necessary and sufficient conditions for a graph *G* to have a perfect matching. These conditions concern eigenvalues of skew-symmetric matrices corresponding to *G*. For a given positive integer *k*, we also give necessary and sufficient conditions for a graph *G* to have match $(G) = k$.

We begin by introducing some required terminology as given in [\[2\].](#page-12-0) Let $A = [a_{ij}]$ be an $n \times n$ real skew-symmetric matrix. The *order* of *A* is *n*, and we denote it by |A|. The *graph* of *A*, denoted by $G(A)$, has the vertex set $\{1, 2, \ldots, n\}$ and the edge set $\{\{i, j\} : a_{ij} \neq 0, 1 \leq i < j \leq n\}$. The set $S^-(G)$ denotes the set of all real skew-symmetric matrices whose graph is *G*. The *maximum skew rank* of *G*, denoted by $MR⁻(G)$, is defined to be max $\{\text{rank}(A): A \in S^{-}(G)\}\$. The maximum skew rank and the matching number of a graph are related as follows.

Theorem 1.2. *(See* $\lbrack 4$ *, [Theorem 2.5\].](#page-12-0))* MR^{$-$}(*G*) = 2match(*G*) *for all graphs G.*

The rank of a real symmetric or skew-symmetric matrix can be determined by its nonzero eigenvalues as follows.

Lemma 1.3. *(See [1, [Corollary](#page-12-0) 2.5.14].) Let A be a real symmetric or skew-symmetric matrix. Then* rank(*A*) *equals to the number of nonzero eigenvalues of A.*

A *full* matching in a graph *G* on *n* vertices is a matching *M* such that $2|M| = n$ or $n-1$, i.e., match $(G) = \lfloor \frac{n}{2} \rfloor$ $(G) = \lfloor \frac{n}{2} \rfloor$ $(G) = \lfloor \frac{n}{2} \rfloor$. In Section 2 we determine existence of a full matching of *G* using nonzero eigenvalues of matrices in *S*−(*G*). In Section [3,](#page-6-0) for a given positive integer *k*, we give necessary and sufficient conditions for *G*, in terms of nonzero eigenvalues of matrices in *S*−(*G*), to have match(*G*) = *k*.

To study matchings in connected graphs we first study matchings in trees. A certain kind of trees called NEB trees is introduced in $[2]$ and it has been shown that any NEB tree has a full matching. We introduce required definitions and notation for NEB trees as given in [\[2\].](#page-12-0)

Notation: Let *T* be a tree, and let $T(v)$ denote the forest obtained from *T* by deleting vertex *v*. Also, let $T' = T_w(v)$ denote the connected component of $T(v)$ that contains

Fig. 1. Tree *T* with subgraphs $T(v_1, \ldots, v_k)$ and $T_{v_k}(v_1, \ldots, v_{k-1})$.

Fig. 2. Tree *T* with subgraphs $T(1, 2)$ and $T_3(1, 2)$.

the neighbor *w* of *v*. *T*^{\prime} is a tree, hence it makes sense to consider $T'(w) = (T_w(v))(w)$, the forest obtained from T' by deleting vertex *w*, and $T'' = (T_w(v))_u(w)$, the connected component of $T'(w)$ that contains the neighbor *u* of *w*, and so on. For simplicity, we denote the tree $(\cdots((T_{v_2}(v_1))_{v_3}(v_2))_{v_4}(v_3))\cdots)_{v_k}(v_{k-1})$ by $T_{v_k}(v_1,v_2,\ldots,v_{k-1})$, and the forest $((\cdots(((T_{v_2}(v_1))_{v_3}(v_2))_{v_4}(v_3))\cdots)_{v_k}(v_{k-1}))(v_k)$ by $T(v_1,\ldots,v_k)$. See Fig. 1.

Example 1.4. Consider the graph in Fig. 2. Delete vertex 1 and consider the connected component that contains the vertex 2. This tree is denoted by $T_2(1)$. Then in this tree delete vertex 2. The obtained forest is denoted by $T(1,2)$. The connected component of $T(1,2)$ that contains the vertex 3 is denoted by $T_3(1,2)$.

Definition 1.5. (See [2, [Definition](#page-12-0) 2.3].) Let *T* be a tree on *n* vertices, and *w* be a vertex of *T*. *T* is defined to have *nearly even branching property at w* (in short, *T* is *NEB at w*) as follows. If $n = 1$, *T* is NEB at *w*. If $n \geq 2$, *T* is NEB at *w* if the following conditions are satisfied:

Fig. 3. Subtree $T_3(1, 2)$ is a minimal non-NEB subtree of *T* with respect to vertex 1.

- (i) $T(w)$ has exactly one odd component if *n* is even, and $T(w)$ has no odd component if *n* is odd; and
- (ii) for each neighbor *v* of *w* in *T*, $T_v(w)$ is NEB at *v*.

Observation 1.6. *If a tree T is not NEB with respect to a vertex v, then there is a vertex w such that T*(*w*) *has at least two odd components.*

Proof. Let $v_1 = v$. If $T(v_1)$ has at least two odd components, then $w = v_1$. Otherwise there are vertices v_2, \ldots, v_k such that $T(v_1, v_2, \ldots, v_k)$ has at least two odd connected components. Let $w = v_k$. Now $T(w)$ has one more branch (at v_{k-1}) than $T_{v_k}(v_1, v_2, \ldots, v_{k-1})$, thus it has at least two odd components. \Box

For a vertex *v*, let $N(v)$ denote the set of all neighbors of *v*. Let T be a tree which is not NEB at a vertex v_1 . There exists v_2, v_3, \ldots, v_k such that $T_{v_k}(v_1, v_2, \ldots, v_{k-1})$ is not NEB at v_k , but every $T_w(v_1, v_2, \ldots, v_k)$ is NEB at w for all $w \in N(v_k) \setminus \{v_{k-1}\}.$ We call such $T_{v_k}(v_1, \ldots, v_{k-1})$ a minimal non-NEB subtree (with respect to v_1).

Example 1.7. Tree T shown in Fig. 3 is not NEB at vertex 1 because $T_3(1, 2)$ is not NEB with respect to vertex 3. But $T_4(1,2,3)$ and $T_5(1,2,3)$ both are NEB with respect to 4 and 5, respectively. Hence, $T_3(1, 2)$ is a minimal non-NEB subtree of T with respect to vertex 1.

The following theorem gives the most important known result we use in this article. It shows that if a tree *T* is NEB at a vertex, then *T* has a full matching.

Theorem 1.8. *(See [2, [Corollary 5.3\].](#page-12-0))* Let G be a connected graph on *n* vertices and λ_1 , $\lambda_2, \ldots, \lambda_n$ *distinct real numbers such that*

$$
\lambda_j = -\lambda_{n+1-j},
$$

for all $j = 1, ..., n$. If G has a spanning tree which is NEB at a vertex, then match(G) = $\lfloor \frac{n}{2} \rfloor$ *and there exists a matrix* $A \in S^-(G)$ *with eigenvalues* $i\lambda_1, \ldots, i\lambda_n$ *.*

Fig. 4. Vertex w_1 is not matched with vertex v where $T_{w_1}(v)$ is an odd component.

2. Characterizations of NEB trees and connected graphs with a perfect matching

[Theorem 1.8](#page-3-0) shows that if a tree *T* is NEB at a vertex, then *T* has a full matching. It is natural to ask if the converse is true. In the next theorem we show that the converse is indeed true.

Theorem 2.1. *Let T be a tree on n vertices. Tree T is NEB with respect to some vertex v if* and only *if* match $(T) = \lfloor \frac{n}{2} \rfloor$.

Proof. The forward direction is proved in $[2,$ [Observation 3.8\].](#page-12-0) For the backward direction, assume *T* is not NEB with respect to any vertex. By [Observation 1.6](#page-3-0) there is a vertex *v* of *T* such that $T(v)$ has at least two odd components. Let $T_{w_1}(v)$ and $T_{w_2}(v)$ be two such odd components.

There are two cases:

- Case 1: *n* is even. Thus, $\lfloor \frac{n}{2} \rfloor = \frac{n}{2}$, that is, *T* has a perfect matching, and exactly one of the neighbors of *v* is matched with *v*. That is, at least one of the w_1 or w_2 are not matched with v . Without loss of generality, assume that w_1 is the vertex which is not matched (see Fig. 4). Then $T_{w_1}(v)$ is a tree with odd number of vertices, hence it has a vertex which is not matched. Furthermore, since *T* has an even number of vertices, it has at least 2 vertices which are not matched. That contradicts the assumption that *T* has a perfect matching.
- Case 2: *n* is odd. Fix v_1 and find a minimal non-NEB subtree of *T* (with respect to v_1), say $T_{v_k}(v_1, \ldots, v_{k-1}) = T'$. Let $v = v_k$. Since T' is a minimal non-NEB subtree of $T, T'(v)$ has at least two odd components.
	- (a) $T'(v)$ has at least 3 odd components, then similar to Case 1, *v* is matched with at most one of its neighbors in an odd component, and other two odd components each have at least one vertex which is not matched. Hence $\text{match}(T) < \lfloor \frac{n}{2} \rfloor.$
	- (b) $T'(v)$ has exactly two odd components, say $T'_{w_1}(v)$ and $T'_{w_2}(v)$. Now, consider $T_v(w_1)$ (see [Fig. 5\)](#page-5-0), which has even number of vertices. If $T_v(w_1)$ is

Fig. 5. Tree *T* and subtrees $T_v(w_1)$ and $T_{w_1}(v)$.

NEB at *v*, then *T* is NEB at w_1 by minimality of *T'*. Otherwise, $T_v(w_1)$ has at least two vertices which are not matched, by Case 1. Furthermore, since *T* has odd number of vertices, then it has at least 3 vertices which are not matched. Thus match $(T) < \lfloor \frac{n}{2} \rfloor$. \Box

We get the following corollary from [Theorem 1.8](#page-3-0) and [Theorem 2.1.](#page-4-0)

Corollary 2.2. Let T be a tree on *n* vertices. Then $\text{match}(T) = \lfloor \frac{n}{2} \rfloor$ *if and only if there is a real skew-symmetric matrix A with distinct eigenvalues whose graph is T.*

Below we mention a rather easy exercise in graph theory, and we will use it to extend the above result to connected graphs.

Lemma 2.3. Let *G* be a connected graph on *n* vertices. Then $\text{match}(G) = \lfloor \frac{n}{2} \rfloor$ if and only *if G* has a spanning tree *T* with match(*T*) = $\lfloor \frac{n}{2} \rfloor$. More specifically, for any matching M (of any size) of G , there is a spanning tree T of G which includes all the edges of M .

Proof. If a spanning tree of *G* has a full matching, then *G* has a full matching. Fix a matching *M* of *G*. Every cycle of *G* contains an edge which is not in *M*. Delete one such edge from *G*, and repeat this process with the obtained graph which is still connected, it contains all edges of *M*, and it has at least one less cycle than *G*. The process stops with a connected acyclic graph (tree) on *n* vertices, since *G* has finitely many cycles. The obtained graph is a spanning tree of G which contains all edges of M . \Box

Theorem 2.4. Let G be a connected graph on n vertices. If $\text{match}(G) = \lfloor \frac{n}{2} \rfloor$, then for any *n* distinct real numbers $\lambda_1, \ldots, \lambda_n$ such that $\lambda_j = -\lambda_{n+1-j}$ for all $j = 1, \ldots, n$, there is a matrix $A \in S^-(G)$ with eigenvalues $i\lambda_1, \ldots, i\lambda_n$. Conversely if there is a matrix $A \in S^{-}(G)$ *with distinct eigenvalues, then* $match(G) = \lfloor \frac{n}{2} \rfloor$.

Proof. Assume that $\text{match}(G) = \lfloor \frac{n}{2} \rfloor$. By [Lemma 2.3](#page-5-0) graph *G* has full matching if and only if it has a spanning tree *T* with a full matching. Also by [Theorem 2.1,](#page-4-0) *T* has a full matching if and only if *T* is NEB with respect to a vertex. Thus, by [Theorem 1.8,](#page-3-0) *G* realizes a real skew-symmetric matrix *A* with the given eigenvalues.

Conversely suppose that there is a real skew-symmetric matrix *A* with distinct eigenvalues whose graph is *G*. Then, by [Lemma 1.3](#page-1-0) and [Theorem 1.2,](#page-1-0)

$$
2\left\lfloor \frac{n}{2} \right\rfloor = \text{rank}(A) \le \text{MR}^-(G) = 2\text{match}(G).
$$

That is, $\frac{n}{2}$ \leq match(*G*). Since match(*G*) $\leq \frac{n}{2}$ for any graph *G*, we have match (G) = $\frac{n}{2}$ \rfloor . \Box

[Theorem 2.4](#page-5-0) immediately implies the following corollary giving a spectral condition for a connected graph to have a perfect matching or a near perfect matching.

Corollary 2.5. *Let G be a connected graph. Then G has a full matching if and only if there is a matrix* $A \in S^{-1}(G)$ *with distinct eigenvalues.*

3. Spectral characterization of graphs with arbitrary matching number

It is known that match(*G*) = *k* if and only if $MR^-(G) = 2k$, i.e., *G* realizes a skew-symmetric with 2*k* nonzero eigenvalues by [Theorem 1.2](#page-1-0) and [Lemma 1.3.](#page-1-0) In this section we prove that these eigenvalues can be any *k* distinct nonzero purely imaginary numbers and their conjugate pairs. Similar to approaches in [\[2,3\]](#page-12-0) we are going to use the Jacobian method, so we need to define an appropriate function and show its Jacobian is nonsingular when it is evaluated at some point.

Let G be a graph on *n* vertices with matching number k , and $k + m$ edges where $m > 0$. Fix a maximum matching M of G and without loss of generality assume $M =$ {{1*,* 2}*,* {3*,* 4}*, ...,* {2*k* − 1*,* 2*k*}}. Assume the *m* edges of *G* that are not in M are of the forms $e_l = \{i_l, j_l\}$, for $l = 1, 2, \ldots, m$. Let $x_1, \ldots, x_k, y_1, \ldots, y_m$ be $k + m$ independent indeterminates and set

$$
x = (x_1, x_2, \ldots, x_k), \text{ and } y = (y_1, y_2, \ldots, y_m).
$$

We define a skew-symmetric matrix of variables where x_j are in the positions corresponding to the edges in M, and y_l are in the positions of the edges not in M. Let $M = M(x, y)$ be an $n \times n$ skew-symmetric matrix whose $(2j - 1, 2j)$ -entry is x_j , $(2j, 2j - 1)$ -entry is $-x_j$, for $j = 1, 2, ..., k$, and for $l = 1, 2, ..., m$ let the (i_l, j_l) -entry of M to be y_l where $i_l < j_l$, and $-y_l$, otherwise. Note that Since match(*G*) = *k*, *G* − {1, 2, ..., 2*k*} has no edges. Thus *M* has the following form.

$$
M = \left[\begin{array}{c|c} N & L \\ \hline -L^T & O \end{array} \right],
$$

where *N* is the upper left $2k \times 2k$ block of *M*, *O* is the square zero matrix of size $n-2k$, and *L* contains only *yl*'s and zeros. Note that *N* contains zero entries, all of the *x^j* 's, and some or none of *y*_{*l*}'s. In particular, the $(2j-1, 2j)$ -th entry of *N* is x_j , for $j = 1, 2, \ldots, k$.

Example 3.1. Consider the following graph *G* on 6 vertices with 6 edges and $match(G) = 2.$

For the above $G, \mathcal{M} = \{ \{1, 2\}, \{3, 4\} \}$ is a maximum matching. So $M = M(x, y)$ would have the following form.

$$
M = M(\boldsymbol{x}, \boldsymbol{y}) = \begin{bmatrix} 0 & \boldsymbol{x_1} & 0 & 0 & 0 & 0 \\ -\boldsymbol{x_1} & 0 & y_1 & y_2 & y_3 & 0 \\ 0 & -y_1 & 0 & \boldsymbol{x_2} & 0 & 0 \\ 0 & -y_2 & -\boldsymbol{x_2} & 0 & y_4 & y_5 \\ 0 & -y_3 & 0 & -y_4 & 0 & 0 \\ 0 & 0 & 0 & -y_5 & 0 & 0 \end{bmatrix}.
$$

A real evaluation *A* of *M* is obtained by assigning real values to indeterminates in *x* and *y*. Clearly such evaluation *A* is a skew-symmetric matrix whose graph is a subgraph of *G* and the eigenvalue of *A* are purely imaginary occurring in conjugate pairs and some zeros. Define the following ordering of the purely imaginary axis of the complex plane: for two numbers *a* and *b* on the imaginary axis of the complex plane let $a \geq b$ if $-a$ i ≥ −*b*i and the equality holds if and only if $a = b$.

Define $F: \mathbb{R}^{k+m} \to \mathbb{R}^n$ by

$$
F(\boldsymbol{x},\boldsymbol{y})=\big(-i\lambda_1(M),-i\lambda_2(M),\ldots,-i\lambda_n(M)\big),
$$

where $\lambda_j(M)$ is the *j*-th largest eigenvalue of M. Note that, some of the middle components of *F* might be zero. Furthermore, since $\lambda_i(M) = -\lambda_{n-i+1}(M)$ for $j = 1, \ldots, n$, *F* is completely defined by half of its components, say the ones in upper half-plane and zeros. Moreover, *M* has at most *k* nonzero eigenvalues in the upper half-plane since $MR^{-}(G) = 2match(G) = 2k$. That is, *F* is completely determined by its first *k* components.

Define $f: \mathbb{R}^{k+m} \to \mathbb{R}^k$ by

$$
f(\boldsymbol{x},\boldsymbol{y}) = (-\mathrm{i}\lambda_1(M), -\mathrm{i}\lambda_2(M), \ldots, -\mathrm{i}\lambda_k(M)).
$$

Let $\lambda_1 > \lambda_2 > \ldots > \lambda_k > 0$ be *k* distinct nonzero purely imaginary numbers. Set $a = (-i\lambda_1, -i\lambda_2, \ldots, -i\lambda_k) \in \mathbb{R}^k$, $b = (0, \ldots, 0) \in \mathbb{R}^m$ and $A = M(a, b)$. Then *A* is the block diagonal matrix

$$
A = \bigoplus_{j=1}^{k} \begin{bmatrix} 0 & -i\lambda_j \\ i\lambda_j & 0 \end{bmatrix} \oplus O_{n-2k}.
$$
 (3.1)

.

That is,

	$\boldsymbol{0}$	$-i\lambda_1$	$\boldsymbol{0}$	$\boldsymbol{0}$	$\boldsymbol{0}$	Ω	
	$i\lambda_1$	$\overline{0}$	$\boldsymbol{0}$	θ	$\boldsymbol{0}$	$\boldsymbol{0}$	
	$\boldsymbol{0}$	$\boldsymbol{0}$	$\boldsymbol{0}$	$-i\lambda_2$	$\boldsymbol{0}$	θ	
	$\boldsymbol{0}$	$\boldsymbol{0}$	$i\lambda_2$	$\overline{0}$	$\boldsymbol{0}$	$\boldsymbol{0}$	
							Ω
$A =$							
	$\boldsymbol{0}$	$\boldsymbol{0}$	$\boldsymbol{0}$	θ	$\boldsymbol{0}$	$-{\rm i}\lambda_k$	
	θ	$\boldsymbol{0}$	$\boldsymbol{0}$	$\boldsymbol{0}$	$i\lambda_k$	$\boldsymbol{0}$	
							Ω

It easy to check that the nonzero eigenvalues of *A* are $\pm \lambda_1, \pm \lambda_2, \ldots, \pm \lambda_k$ and consequently $f\bigg|_A = f(\mathbf{a}, \mathbf{b}) = (-i\lambda_1, -i\lambda_2, \ldots, -i\lambda_k)$. We want to show that the Jacobian of f evaluated at the point (a, b) is nonsingular. It is known that the eigenvalues and eigenvectors of a matrix with distinct eigenvalues are continuous differentiable functions of the entries of the matrix [\[8\].](#page-12-0) The following lemma shows the derivative of the nonzero eigenvalues of a skew-symmetric matrix with 2 k distinct nonzero eigenvalues and $n - 2k$ zero eigenvalues with respect to the entries of the matrix, in terms of the entries of their corresponding eigenvectors.

Lemma 3.2. *Let A be an n* × *n real skew-symmetric matrix with distinct nonzero eigenvalues* $\lambda_1, \lambda_2, \ldots, \lambda_k$ *in the upper half-plane, and corresponding unit eigenvectors* v_1, v_2, \ldots, v_k . Let $A(t) = A + tE_{rs} - tE_{sr}$, for $t \in (-\varepsilon, \varepsilon)$, where ε is a small pos*itive number.* Also, let $\lambda_j(t)$ be the *j*-th *largest eigenvalue* of $A(t)$ *with corresponding eigenvector* $\mathbf{v}_j(t)$ *,* and \mathbf{v}_{j_r} denote the r-th entry of the vector \mathbf{v}_j *. Then*

$$
\frac{d\lambda_j(t)}{dt}\Big|_{t=0}=2{\rm i}\, {\rm Im}(\overline{\bm v_{j_r}}\bm v_{j_s}),
$$

where $\text{Im}(z)$ *denotes the imaginary part of the complex number* z *.*

Proof. Note that $A(t)$, $\lambda_j(t)$ and $v_j(t)$ are continuous functions of *t*, so $A(0) = A$, $\lambda_j(0) = \lambda_j, \mathbf{v}_j(0) = \mathbf{v}_j$, and when $t \to 0$ we have

$$
A(t) \to A,
$$

\n
$$
\lambda_j(t) \to \lambda_j,
$$

\n
$$
\mathbf{v}_j(t) \to \mathbf{v}_j.
$$

Furthermore,

$$
\dot{A}(0) = E_{rs} - E_{sr},
$$

and

$$
A(t)\mathbf{v}_j(t) = \lambda_j(t)\mathbf{v}_j(t).
$$

Differentiating both sides with respect to *t* we get

$$
\dot{A}(t)\boldsymbol{v}_j(t) + A(t)\dot{\boldsymbol{v}}_j(t) = \dot{\lambda}_j(t)\boldsymbol{v}_j(t) + \lambda_j(t)\dot{\boldsymbol{v}}_j(t).
$$

Set $t = 0$, then

$$
(E_{rs} - E_{sr})\boldsymbol{v}_j + A\boldsymbol{v}_j(0) = \lambda_j(0)\boldsymbol{v}_j + \lambda_j\boldsymbol{v}_j(0).
$$

Multiplying both sides by $\overline{v_j}^T$ from left we get

$$
\overline{\boldsymbol{v}_j}^T (E_{rs} - E_{sr}) \boldsymbol{v}_j + \overline{\boldsymbol{v}_j}^T A \boldsymbol{v}_j(0) = \dot{\lambda}_j(0) \overline{\boldsymbol{v}_j}^T \boldsymbol{v}_j + \lambda_j \overline{\boldsymbol{v}_j}^T \boldsymbol{v}_j(0).
$$

Since *A* is skew-symmetric $A\overline{v_j} = -\lambda_j \overline{v_j}$. Hence

$$
\overline{\boldsymbol{v}_j}^T A = (A^T \overline{\boldsymbol{v}_j})^T = (-A \overline{\boldsymbol{v}_j})^T = (-(-\lambda_j \overline{\boldsymbol{v}_j}))^T = \lambda_j \overline{\boldsymbol{v}_j}^T.
$$

Also,

$$
\overline{\boldsymbol{v}_j}^T (E_{rs} - E_{sr}) \boldsymbol{v}_j = \overline{\boldsymbol{v}_{j_r}} \boldsymbol{v}_{j_s} - \overline{\boldsymbol{v}_{j_s}} \boldsymbol{v}_{j_r} = 2i \operatorname{Im}(\overline{\boldsymbol{v}_{j_r}} \boldsymbol{v}_{j_s}).
$$

Thus

$$
2\mathrm{i}\,\mathrm{Im}(\overline{\bm{v}_{j_r}}\bm{v}_{j_s})+\lambda_j\overline{\bm{v}_j}^T\bm{v}_j(0)=\dot{\lambda}_j(0)\overline{\bm{v}_j}^T\bm{v}_j+\lambda_j\overline{\bm{v}_j}^T\dot{\bm{v}}_j(0).
$$

The second term in left hand side is equal to the second term in right hand side, and v_j 's are unit vectors, that is, $\overline{v_j}^T v_j = 1$. Hence

$$
2i \operatorname{Im}(\overline{\boldsymbol{v}_{j_r}} \boldsymbol{v}_{j_s}) = \lambda_j(0). \quad \Box
$$

Corollary 3.3. For M, A, and λ_i 's defined as above, let $r = 2l - 1$, $s = 2l$, and x_l be the *entry in the* (*r, s*) *position of M. Then we have*

$$
\frac{\partial}{\partial x_l}(-i\lambda_j(M))\Big|_A = \begin{cases} 1, & \text{if } j = l, \\ 0, & \text{otherwise.} \end{cases}
$$

Proof. Note that for *A* we have

$$
\boldsymbol{v}_j = \frac{1}{\sqrt{2}} \begin{bmatrix} 0 & \cdots & 0 & \mathrm{i} & -1 & 0 & \cdots & 0 \end{bmatrix}^T,
$$

where the nonzero entries are at $2j - 1$ and $2j$ positions. Also note that

$$
\frac{\partial}{\partial x_l} \big(\lambda_j(M) \big) \Big|_A = \frac{\mathrm{d} \lambda_j(t)}{\mathrm{d} t} \Big|_{t=0}.
$$

Then by [Lemma 3.2](#page-8-0)

$$
\frac{\partial}{\partial x_l} \left(-i \lambda_j(M) \right) \Big|_A = (-i) 2i \operatorname{Im} \left(\overline{v_{j_{2l-1}}} v_{j_{2l}} \right)
$$

$$
= \begin{cases} 2 \operatorname{Im} \left(\frac{-i}{\sqrt{2}} \frac{-1}{\sqrt{2}} \right), \text{ if } j = l, \\ 0, \text{ otherwise.} \end{cases}
$$

$$
= \begin{cases} 1, \text{ if } j = l, \\ 0, \text{ otherwise.} \end{cases}
$$

This completes the proof. \square

Corollary 3.4. *For the matrix A and function f defined as above we have*

$$
\operatorname{Jac}(f)\Big|_{A}=I_k,
$$

where I_k *denotes the* $k \times k$ *identity matrix. Hence,* $Jac(f) \Big|_A$ *is nonsingular.*

Now we are ready to prove the main result of this section which characterizes the graphs with matching number *k*. We will use the Implicit Function Theorem, mentioned below. For a full treatment of the topic see [\[5\].](#page-12-0)

Theorem 3.5 *(Implicit Function Theorem).* Let $F: \mathbb{R}^{s+r} \to \mathbb{R}^s$ be a continuously differ*entiable function on an open subset U of* \mathbb{R}^{s+r} *defined by*

$$
F(\boldsymbol{x},\boldsymbol{y})=(F_1(\boldsymbol{x},\boldsymbol{y}),F_2(\boldsymbol{x},\boldsymbol{y}),\ldots,F_s(\boldsymbol{x},\boldsymbol{y})),
$$

where $\mathbf{x} = (x_1, \ldots, x_s) \in \mathbb{R}^s$, $\mathbf{y} = (y_1, \ldots, y_r) \in \mathbb{R}^r$, and F_i 's are real valued multivariate functions. Let (a, b) be an element of U with $a \in \mathbb{R}^s$ and $b \in \mathbb{R}^r$, and c be an element $of \mathbb{R}^s$ *such that* $F(a, b) = c$ *. If*

$$
\operatorname{Jac}_x(F) \Big|_{(a,b)} = \left[\frac{\partial F_i}{\partial x_j} \Big|_{(a,b)} \right]_{s \times s}
$$

is nonsingular, then there exist an open neighborhood V of a and an open neighborhood W of b such that $V \times W \subseteq U$ *such that for each* $y \in W$ *there is an* $x \in V$ *with* $F(\mathbf{x}, \mathbf{y}) = \mathbf{c}$. Furthermore, for any $(\bar{\mathbf{a}}, \bar{\mathbf{b}}) \in V \times W$ such that $F(\bar{\mathbf{a}}, \bar{\mathbf{b}}) = \mathbf{c}$, $Jac(F)\Big|_{(\bar{\mathbf{a}}, \bar{\mathbf{b}})}$ *is also nonsingular.*

Theorem 3.6. Let G be a graph on *n* vertices, and $\lambda_1 > \lambda_2 > \ldots > \lambda_k > 0$ be k distinct *nonzero purely imaginary numbers where* $2k \leq n$ *. Then* $match(G) = k$ *if* and only *if*

- *(a) there is a matrix* $A \in S^{-1}(G)$ *whose eigenvalues are* $\pm \lambda_1, \pm \lambda_2, \ldots, \pm \lambda_k$ *and* $n 2k$ *zeros, and*
- *(b)* for all matrices $A \in S^{-}(G)$, *A* has at most 2*k* nonzero eigenvalues.

Proof. Assume that (a) and (b) hold. Then (a) and [Lemma 1.3](#page-1-0) imply that $MR^-(G) \ge$ 2*k*. Furthermore (b) and [Lemma 1.3](#page-1-0) imply that $MR^{-}(G) \leq \text{rank}A = 2k$. Thus $MR^{-}(G) = 2k$. By [Theorem 1.2](#page-1-0) we have match $(G) = \frac{MR^{-}(G)}{2} = \frac{2k}{2} = k$.

Now assume that $m \text{tch}(G) = k$. If *G* is a disjoint union of edges, then the matrix *A* given by [\(3.1\)](#page-8-0) has the desired properties. Assume that there is an edge which is not in a maximum matching, that is, *G* has $k + m$ edges where $m > 0$. Consider the function *f*, and the matrices *M* and *A* as above. Note that $f\bigg|_A = (-i\lambda_1, -i\lambda_2, \ldots, -i\lambda_k)$, and $Jac(f)$ $\Big|_A$ is nonsingular, by [Corollary 3.4.](#page-10-0) Then by the Implicit Function Theorem (Theorem 3.5) there are open sets $U \in \mathbb{R}^k$ and $V \in \mathbb{R}^m$, such that $(-i\lambda_1, \ldots, -i\lambda_k) \in U$ and $(0, \ldots, 0) \in V$, and for any $(\varepsilon_1, \ldots, \varepsilon_m) \in V$, there is a $(-i\lambda_1, \ldots, -i\lambda_k) \in U$ close $\text{to } (-i\lambda_1, \ldots, -i\lambda_k)$, such that

$$
f(-i\widehat{\lambda_1},\ldots,-i\widehat{\lambda_k},\varepsilon_1,\ldots,\varepsilon_m)=(-i\lambda_1,\ldots,-i\lambda_k).
$$

Since *V* is an open neighborhood of $(0, \ldots, 0) \in \mathbb{R}^m$, one can choose all $\varepsilon_i \neq 0$. Let $A = M(-i\lambda_1,\ldots,-i\lambda_k,\varepsilon_1,\ldots,\varepsilon_m)$. Then eigenvalues of A are $(-i\lambda_1,-i\lambda_2,\ldots,-i\lambda_k)$ and graph of *A* is *G*. That is (*a*) holds. Also, by [Theorem 1.2](#page-1-0) and [Lemma 1.3,](#page-1-0) (b) holds. \Box

Note that for a given graph *G* with matching number *k*, there might exist skewsymmetric matrices with less than 2*k* nonzero eigenvalues whose graph is *G*. One easy example is the complete bipartite graph $K_{n,n}$, $n \geq 2$. The matching number of $K_{n,n}$ is *n* and its skew-adjacency matrix $A = xy^T - yx^T$, where $x = \begin{bmatrix} 1 \\ 1 \end{bmatrix}^T$ and $y = \begin{bmatrix} 1 & 2 & 1 \end{bmatrix}^T$ and **1** is the all ones vector of order *n*, has only two nonzero eigenvalues $\pm n\overline{i}$.

Remark 3.7. [Theorem 3.6](#page-11-0) shows that the graphs *G* of order *n* whose matching number is *k* are precisely those graphs with the maximum skew rank 2*k* such that for any given set of *k* distinct nonzero purely imaginary numbers there is a real skew-symmetric matrix *A* with graph *G* whose spectrum consists of the given *k* numbers, their conjugate pairs and $n - 2k$ zeros.

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